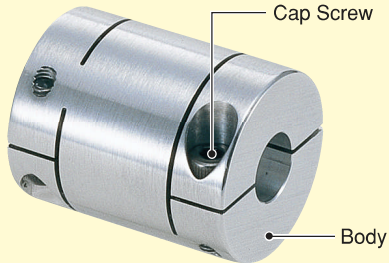


XRP



Configuration



Features

Merits

High Precision

- High Precision Rigid Coupling
- The utmost limit of accuracy in coaxiality, bore diameters, and run-out
- Inspection report documentation included with each product
- Light Weight, Low Moment of Inertia, High Response
- Finished products featuring two different end bore diameters available in stock

Material & Finish

| | |
|-----------|------------------------------|
| Body | A7075 |
| Cap Screw | SCM435, Black Oxide Coating* |

* Stock screws can be replaced with stainless steel screws. Please take advantage of our stainless steel screw option. For more information please refer to page 16.

| Application | |
|---|---|
| Servomotor | ◎ |
| Stepping Motor | ◎ |
| General-Purpose Motor | — |
| Encoder | ◎ |
| Special Characteristics | |
| Zero Backlash | ◎ |
| High Torsional Stiffness | ◎ |
| High Torque | ● |
| Allowable Misalignment | — |
| Vibration Absorption | — |
| Electrical Insulation | — |
| Corrosion Resistant (All Stainless Steel) | — |

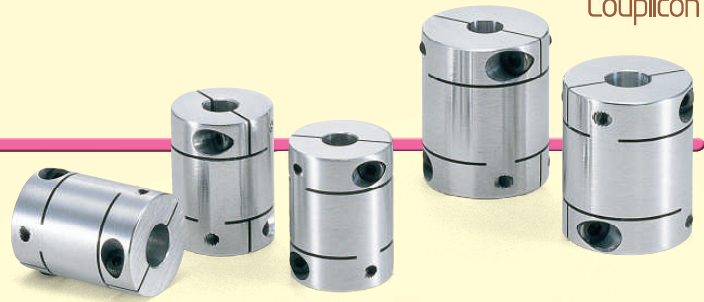
◎ : Excellent ● : Very Good

When Ordering

Specify product code and both bore diameters.

XRP-19C-6×8

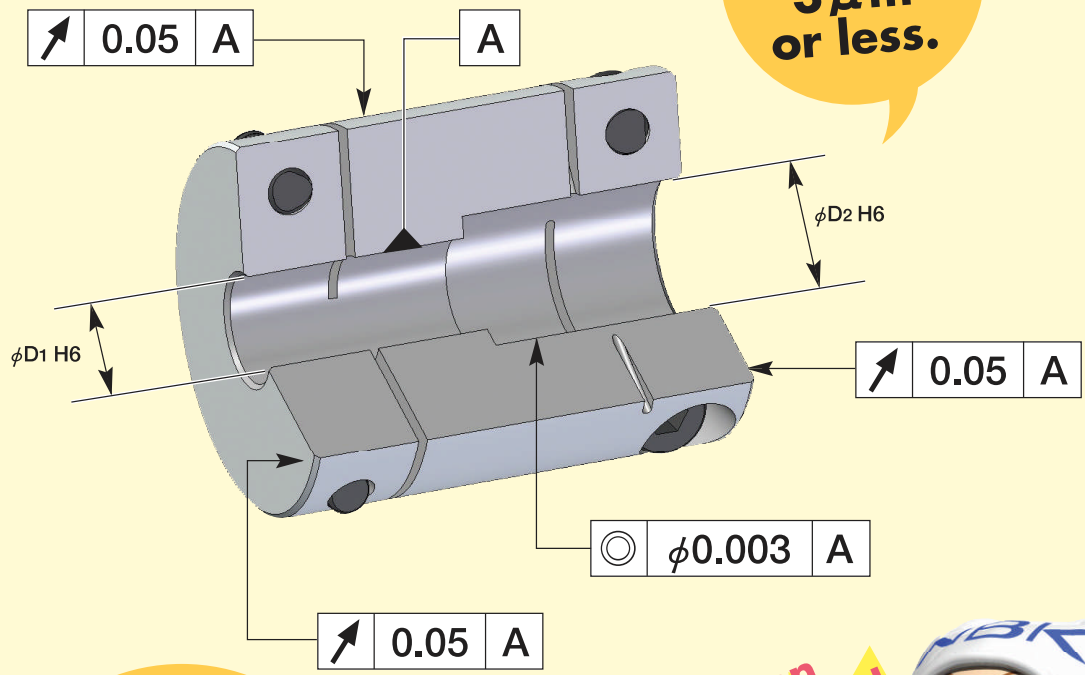
Product Code
D₁
D₂



In Pursuit of High Precision

- Coaxial level between bores is $3\ \mu\text{m}$ or less.
- Tolerance of bore is H6.
- Run-out of the coupling on outer diameter and side run-out, using the bore center as a reference, are both kept below $50\ \mu\text{m}$.
- Construction of shaft clamp takes rotational balance into special account. This minimizes unbalance.
- Manufactured from extra super duralumin (A7075) - the highest strength aluminum alloy.

**Coaxial Level
3 μm
or less.**



High Precision Rigid Coupling

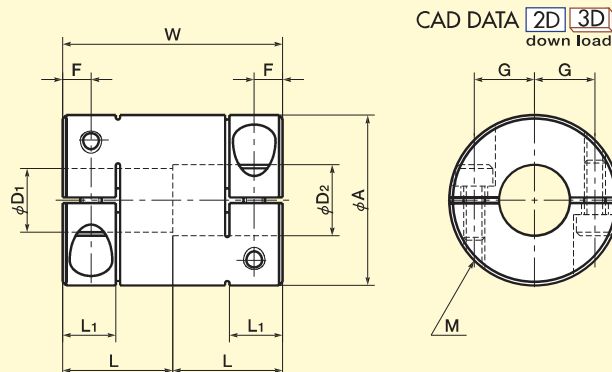
Micron Precision!



■ Regarding Shaft Insertion Length

Shaft insertion length should be greater than L_1 (clamp area length) with a maximum length of L .
 In order to maintain high precision, please insert shaft as close as possible to L .
 However, take care that the two shaft ends do not touch.

If shaft insertion length is less than L_1 , run out and coaxial deviation may result.



Dimensions

unit:mm

| Product Code | A | L | L ₁ | W | F | G | M | Wrench Torque (N·m) |
|--------------|----|----|----------------|----|------|------|------|---------------------|
| XRP-16C | 16 | 10 | 5 | 20 | 2,6 | 5 | M2 | 0,5 |
| XRP-19C | 19 | 13 | 6,5 | 26 | 3,5 | 6,25 | M2,5 | 1 |
| XRP-24C | 24 | 15 | 7 | 30 | 3,75 | 7,75 | M3 | 1,5 |
| XRP-34C | 34 | 20 | 8 | 40 | 4 | 12 | M3 | 1,5 |
| XRP-39C | 39 | 24 | 10 | 48 | 5 | 14,5 | M4 | 2,5 |

| Product Code | Stock Bore Diameters | | |
|--------------|--------------------------------|-------|-------|
| | D ₁ ×D ₂ | | |
| XRP-16C | 5× 5 | 5× 6 | 6× 6 |
| XRP-19C | 6× 6 | 6× 8 | 8× 8 |
| XRP-24C | 8× 8 | 8×10 | 10×10 |
| XRP-34C | 10×10 | 10×12 | 12×12 |
| XRP-39C | 12×12 | 12×14 | 15×15 |

- All products come with cap screws.
- Recommended tolerance for shaft diameters is h6 and h7.
- Specialty goods with nonstandard bore diameters can also be produced. Please contact the customer service for more information.

Specifications

| Product Code | Max. Bore (mm) | Rated* Torque (N·m) | Max.* Torque (N·m) | Max. Rotational Frequency (min ⁻¹) | Moment** of Inertia (kg·m ²) | Mass** (g) |
|--------------|----------------|---------------------|--------------------|--|--|------------|
| XRP-16C | 6 | 0,6 | 1,2 | 39000 | 3,1×10 ⁻⁷ | 9 |
| XRP-19C | 8 | 1,4 | 2,8 | 33000 | 8,0×10 ⁻⁷ | 15 |
| XRP-24C | 10 | 2,3 | 4,6 | 26000 | 2,7×10 ⁻⁶ | 32 |
| XRP-34C | 15 | 2,8 | 5,6 | 18000 | 1,4×10 ⁻⁵ | 87 |
| XRP-39C | 18 | 4,7 | 9,4 | 16000 | 3,9×10 ⁻⁵ | 140 |

* Adjustment of rated and maximum torque specifications for load fluctuations is not required.

For more detailed information, please refer to For Better Drive on page 34.

** Moment of inertia and mass figures based on maximum bore dimensions.