



- Multi-function unit for incremental encoders
- Position display, tachometer, counter, stopwatch or timer
- Touchscreen and graphic display
- Full text menu for intuitive setup
- Universal inputs (HTL, TTL, RS422) for NPN, PNP, Namur sensors
- 4 digital control outputs & serial interface (option)
- 16 bit analog output (option)
- 2 relays outputs (option)



LD350 • LD355

LD350: AB input

LD355: AB /AB input

FUNCTIONS

Position indicator, counter, time or stopwatch display, speed display, linearization function (24 points), filtering, start/stop suppression, scaling

ENVIRONMENTAL SPECIFICATIONS

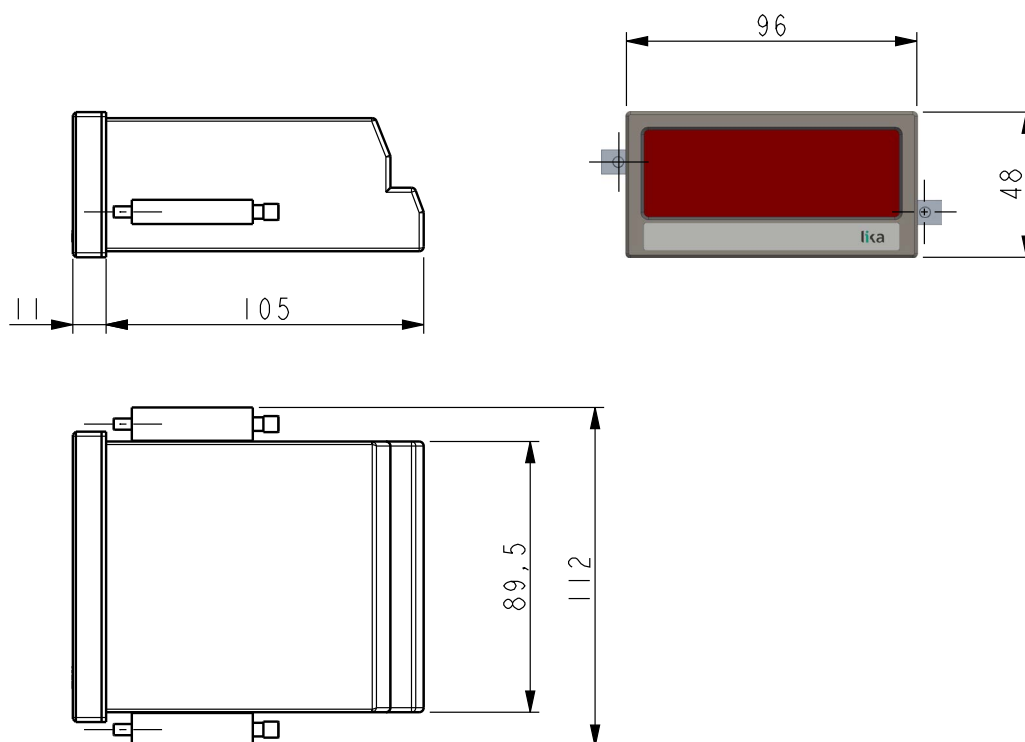
Operating temperature range:	-20°C +60°C (-4°F, +140°F)
Storage temperature range:	-25°C +70°C (-13°F, +158°F)
Protection:	IP65 front, IP20 back

MECHANICAL SPECIFICATIONS

Dimensions:	96 x 48 x 116 mm ³
Cut out:	91 x 43 mm ²
Display:	LCD backlight, touchscreen 8 digits (-99999999 ÷ 99999999) switchable colour (red, green, yellow)

ELECTRICAL SPECIFICATIONS

Power supply:	18Vdc +30Vdc 115 ÷ 230 Vac (option PM)
Consumption:	100 mA without sensor 3 VA with option PM)
Counting frequency:	250 kHz max. (encoder inputs) 1 MHz max. in differential mode 10 kHz max. (control inputs)
Encoder inputs:	LD350: AB (2 x PNP, NPN, or Namur/HTL) LD355: AB /AB (4 x TTL, HTL, RS422, HTL diff.)
Control inputs:	3 x HTL, PNP, max. 10 kHz
Serial interface:	RS232, max 38400 baud (option AVI1, DO1) RS485, max 38400 baud (option AVI2, DO2)
Outputs:	4 digital outputs, PNP, 5÷30V max. 200 mA (option DO1, DO2) 2 relays outputs, potential free changeover, max. 250 Vac/150Vdc (option RO) 1 analogue output, 16 bit, ± 10V or 0/4-20 mA (option AVI1, AVI2)



LD350 • LD355

Order code

LD350	-	XX	-	XXXX	-	XX
LD355		Ⓐ		Ⓑ		Ⓒ

Ⓐ POWER SUPPLY

P8 = +18 +30Vdc
 PM = 115 ÷ 230 Vac (option)

Ⓑ OUTPUT

- = no option
 AVI1 = 16 bit analogue output
 4 digital outputs
 RS232 interface
 AVI2 = 16 bit analogue output
 4 digital outputs
 RS485 interface
 DO1 = 4 digital outputs
 RS232 interface
 DO2 = 4 digital outputs
 RS485 interface

Ⓒ RELAYS OUTPUT

- = no option
 RO = 2 relays outputs